

# Argo-España

*Parte de la estrategia global de observación del océano*



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## Report on Delayed Mode for Argo float WMO 1900378

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## Delayed Mode Quality Control for Argo float WMO 1900378

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A. González-Santana - P. Vélez-Belchí  
Instituto Español de Oceanografía

# 1 Introduction

The Delayed Mode Quality Control (DMQC) has been developed for float WMO 1900378 and delivered on 18/12/2017 to ifremer.

Transmission system	ARGOS
Transmission ID	40825 02412
Platform Model	PROVOR n/a n/a
Platform ID	OIN-04-SP-S2-05
Sensors	SBE41CP SBE41CP SBE41CP
Sensores s/n	8944 8944 8944
Data Centre (Format Version)	IF (3.1)
Project Name	ARGO SPAIN
Data Centre (Format Version)	IF (3.1)
Project Name	ARGO SPAIN
Float Owner	
PI Name	Daniel BALLESTERO
Parking Depth (dbar)	1000 (1000 1000 )
Profile depth (dbar)	2000 (2000 2000 )
Number of Profiles	2
Status	Inactive
Deployment Date	10-Dec-2005 00:00:00
Deployment Position	Lat 9.00 Lon -90.00
Last Surfacing Date	31-Dec-2005 05:59:00
Deployed Position	Lat 8.83 Lon -89.87
Age (years)	0.1
Voltage (v)	
Sensors	SBE41CP SBE41CP SBE41CP

Table 1. Technical information of the float.

A deep analysis could not be developed due to the lack of data. A total of 2 profiles were unsuccessfully developed. Also, trajectory data was reported from the beginning to the end during 0.1 years. There is no solid reason to explain the lack of data for 1900378. There is no battery information reported.

Pressure surface offset and internal vacuum malfunction was reported. There is no clear information about the mounted sensors but since the float was deployed in 2003, it might be appropriate to consider the next information about pressure sensors: "Prior 2003, Druck company has rectified some issues and the sensors were thought to be very stable, that is, until a recent discovery of a significant number of sensors now appear to suffer from a 'microleak', whereby oil leaks from the inner sensor chamber through fine cracks in the seals at the back of the sensor."

Barker, P. M., J. R. Dunn, C. M. Domingues, and S. E. Wijffels, 2011: Pressure Sensor

Drifts in Argo and Their Impacts. *Journal of Atmospheric and Oceanic Technology*, 28, 1036-1049, <http://dx.doi.org/10.1175/2011JTECHO831.1>

Several checks were performed: Pressure values were studied to avoid possible TNDP anomalies. The Thermal Mass Error was also calculated in order to avoid possible errors due to the temperature gradients. The Owens and Wong Objective Mapping Analysis (2003) was applied to achieve an optimum calibration of the salinity. Drift or bias evidence cannot be seen in the salinity measurement for WMO 1900378 float and the available profiles are not reliable (out of climatology). Therefore after the manual evaluation and inspection, no adjustment is needed according to Argo Quality Control Manual: PSAL ADJUSTED = PSAL (original value), PSAL ADJUSTED ERROR = Uncertainty provided by PI, PSAL ADJUSTED QC = 3.

## 2 Salinity correction from the OW method

The following parameters has been set up for the Owens and Wong Objective Mapping Analysis method:

Config_max_casts	2
use_pv	0
scale_long_large	2
scale_lat_large	2
scale_long_small	1
scale_lat_small	1
scale_phi_small	0
scale_phi_large	0
scale_age	10
p_delta	250
p_exclude	200

Table 2. Owens and Wong Objective Mapping Analysis method parameters .

Figure 1: Pressure record (a). Voltage record (b).

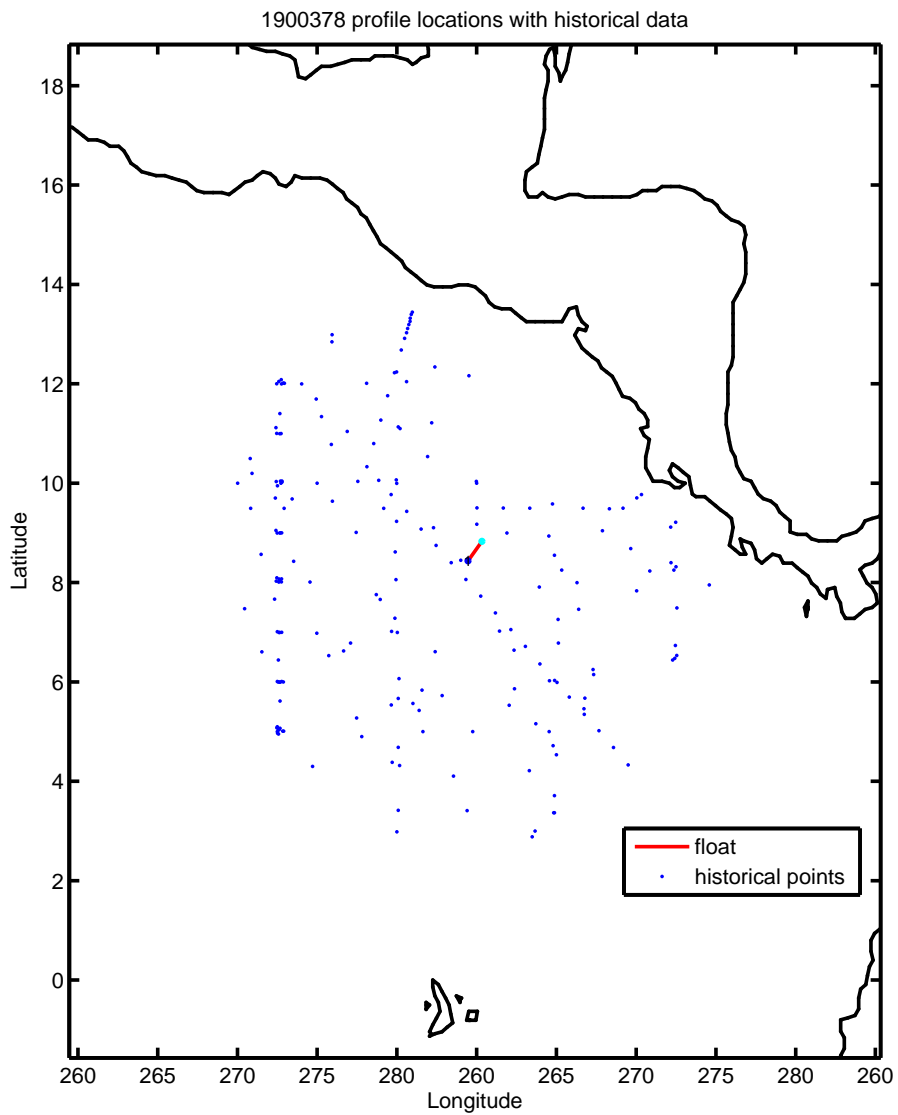
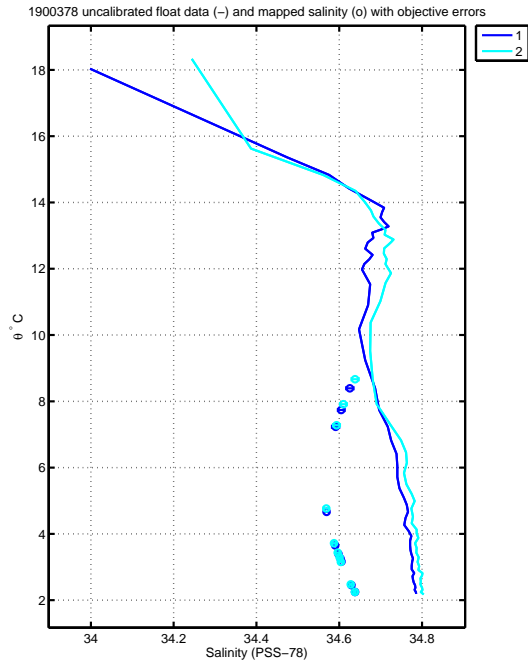
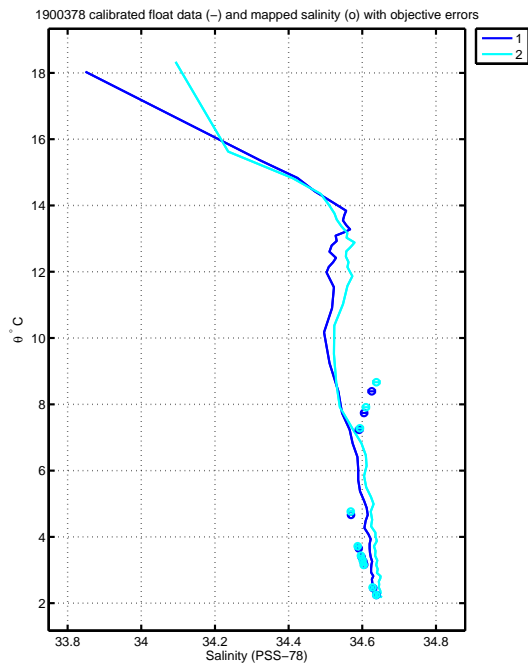


Figure 2: Historical points around the current ARGO float trajectory. These historical points are used by Owens and Wong Objective Mapping Analysis to make a model for an ARGO float data calibration.



(a) T-S Diagram



(b) T-S Diagram after a potential calibration

Figure 3: Both graphs show T-S diagrams before and after a potential calibration. This is useful to identify water masses, to detect some possible offsets or to identify some anomalous profiles.

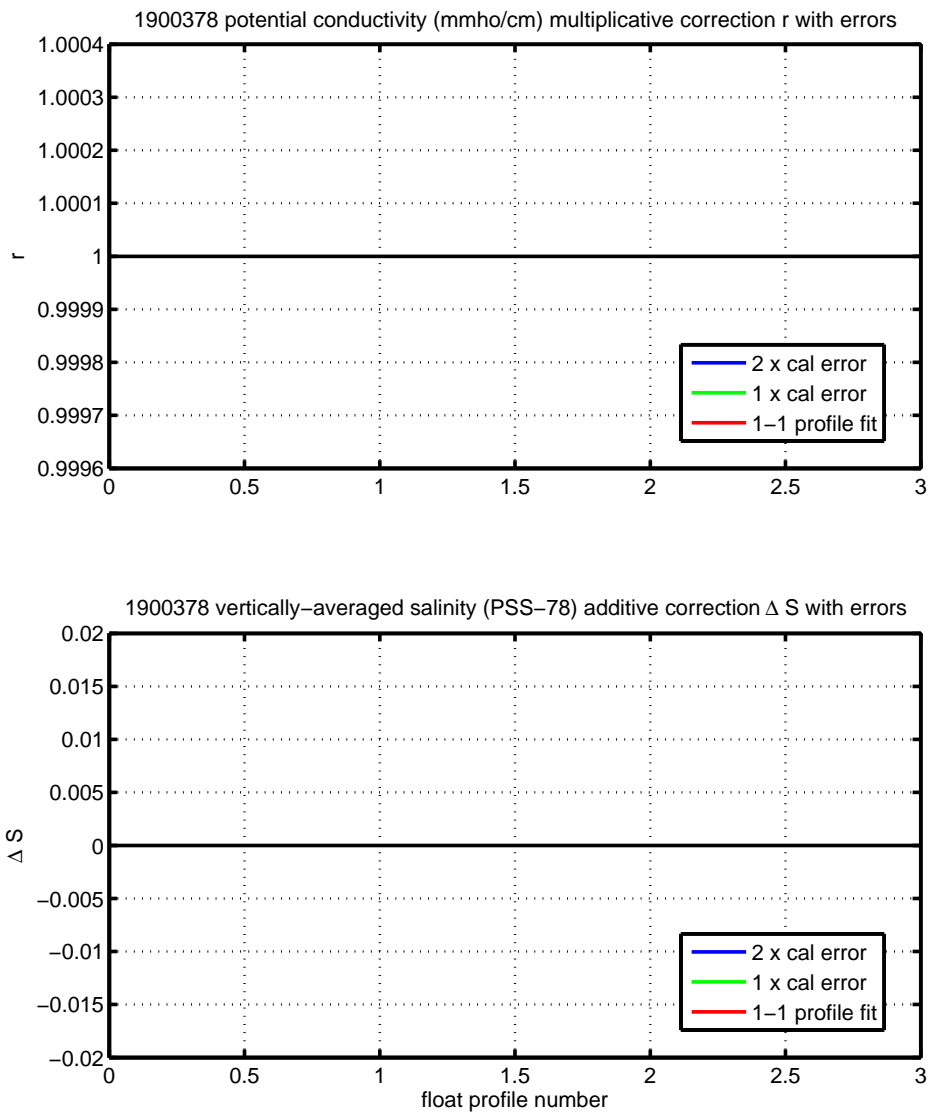


Figure 4: Salinity variation between each profile. Owens and Wong Objective Mapping Analysis builds its model based in a programmed number of break points.

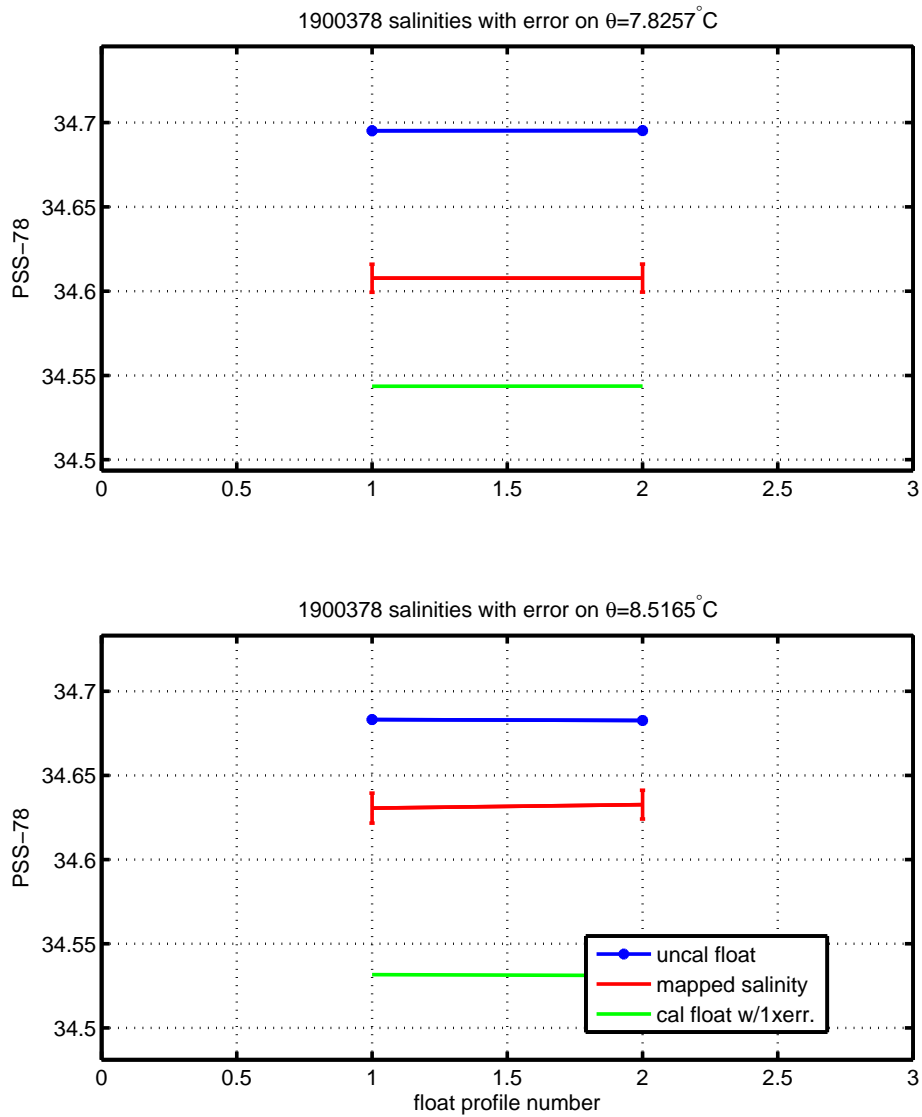
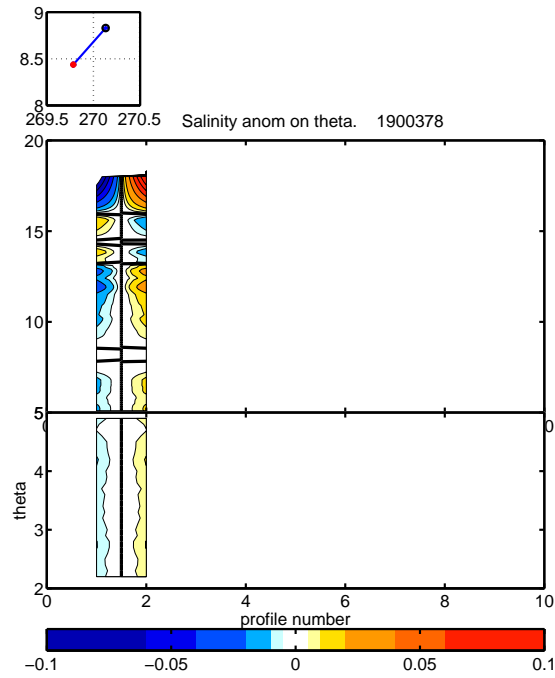
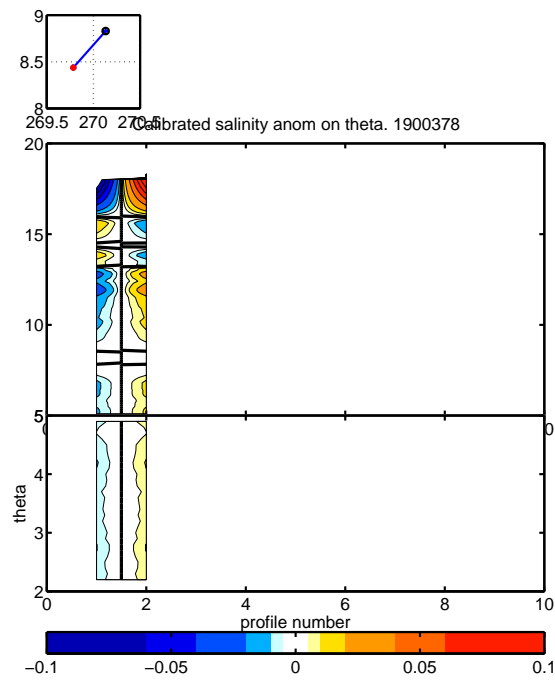


Figure 5: This figure gives a rough idea how uncalibrated (blue line) and calibrated (green line) signals fit each other. Bear in mind that mapped salinity depends on the historical hydrographic points of the area (Figure 1). The less historical points, the less approximated is the model.



(a) Original salinity variation



(b) Calibrated salinity variation

Figure 6: Brians King plots. Both show the salinity variation for an each level of theta per profile. A colored scale indicates the salinity variation (white color indicates no variation). Comparing both uncalibrated and calibrated plots, significant salinity variations can be identified.

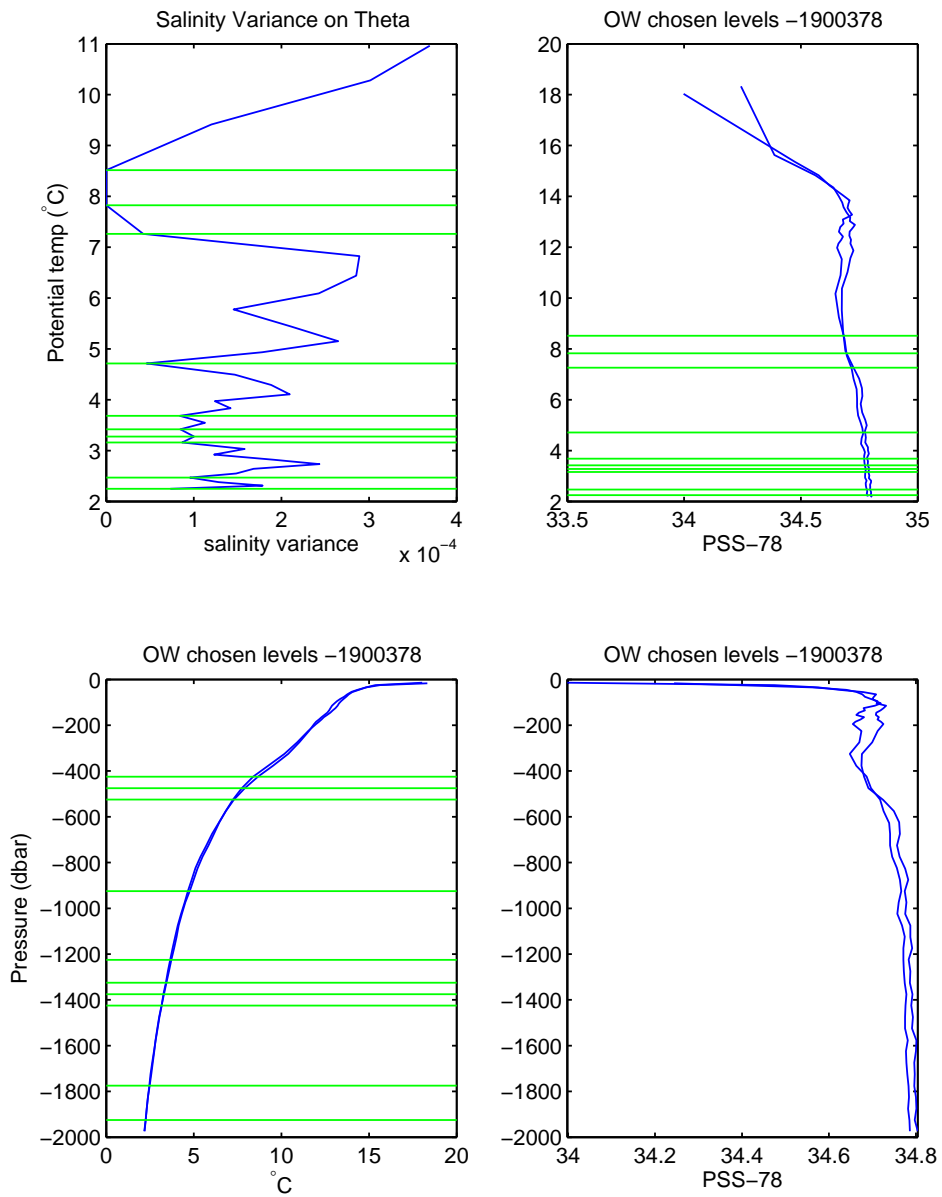


Figure 7: Theta levels are chosen by Owens and Wong Objective Mapping Analysis. The model identifies automatically the theta levels where the salinity variations are smaller.